



LEGO EV3 Course

Curriculum 38 Sessions

course title Core EV3

Session Plan For

2020-21

EV3 Core Set is a hands-on, cross-curricular STEM solution that engages students by providing the resources to design, build and program their creations while helping them develop essential skills such as creativity, critical thinking, collaboration, and communication. A Core Set supports two students and comes with a getting-started guide, video tutorials, and standards-aligned lesson plans.

The system includes the EV3 Intelligent Brick, a compact and powerful programmable computer that makes it possible to control motors and collect sensor feedback using the intuitive icon-based programming and data logging software that is delivered with the set.

The set is delivered in a sturdy storage bin with a sorting tray, three Servo Motors, five Sensors (Gyro, Ultrasonic, Color and 2x Touch), a EV3 Rechargeable DC Battery (with charging cable) and connecting cables.

Building instructions and other resources are also provided.

All Students will be provided with the certification on successful completion of the course.



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| BEGINNER | Session 1 | Mindstorms EV3 & its Parts |
| | Session 2 | Forward & Backward Motion |
| | Session 3 | Steer the Bot |
| | Session 4 | Display on EV3 screen |
| | Session 5 | Touch Sensor ~ Bumpbot |
| | Session 6 | Color Sensor |
| | Session 7 | Repeated Actions (Loops) |
| | Session 8 | Line Following Robot |
| EXPERT PROFICIENT | Session 9 | DIY 'Line Follower that Stops' |
| | Session 10 | IR Sensor ~ Obstacle Avoidance |
| | Session 11 | Interfacing Motion Sensor |
| | Session 12 | Concept of Gear - I |
| | Session 13 | Concept of Gear - II |
| | Session 14 | Building a Tri Bot |
| | Session 15 | Testing a Tri bot |
| | Session 16 | Simple Grabbers |
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| | Session 18 | DIY 'Dog Follower Robot' |
| | Session 19 | Grabber using Worm Gear |
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| | Session 21 | Challenge 'Grid Solving I' |
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| | Session 23 | Bot Ball I (Building) |
| | Session 24 | Bot Ball I (Programming) |
| | Session 25 | Grabber Bot (Building) |
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| | Session 31 | Build a Treaded Bot |
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| | Session 35 | Drawing Bot |
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| | Session 38 | Cruise Control |

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